

***Design and Integration of  
Suspension, Brake and Steering Systems  
for a Formula SAE Race Car***

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**Final Report**

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**MAE 340/440**

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# “Behind the Wheels”

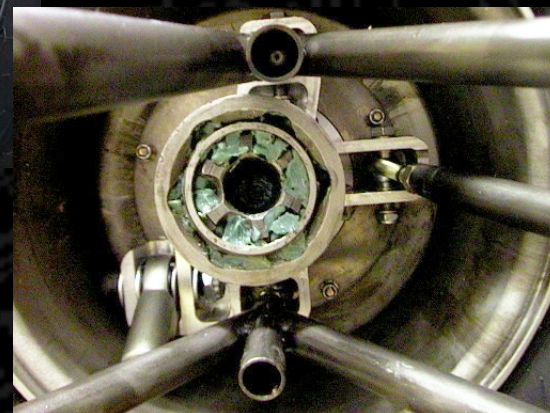
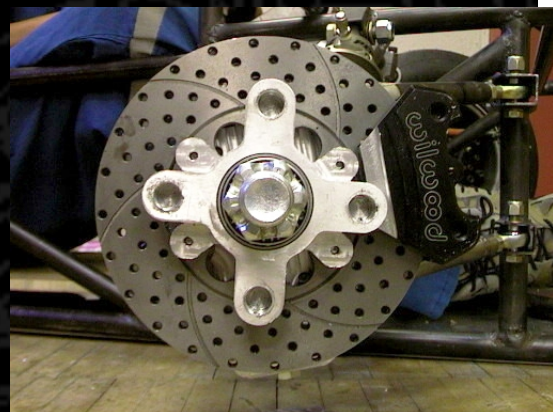
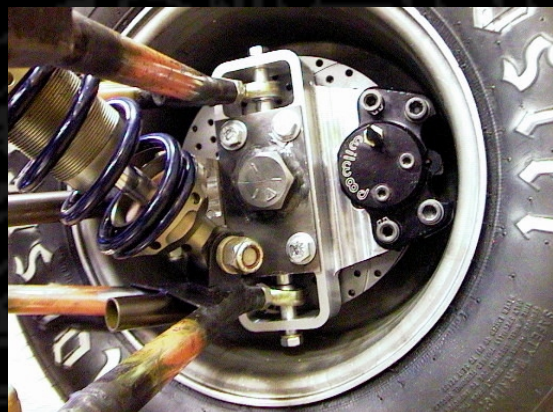
Intro/Update

Front axle

Rear axle

Specifications

The Future





# Vehicle Control Systems

Intro/Update

- **Suspension System**

- Fall semester's focus

- Kinematics (motion of wheel)

- Dynamics (behavior of the wheel and car)

Front axle

Rear axle

- **Steering System**

- Control, stability, consistency

Specifications

- **Brake System**

- Control, efficiency, effectiveness

The Future

- **Philosophies: Reliability, adjustability...**

# Suspension Update

Intro/Update

Front axle

Rear axle

Specifications

The Future

- Repositioned all shock absorber attachment points for reduced bending loads and optimized load paths
- Grounded rear track rod/toe link for strength
- Completed final parts for all corners of the car
- Rethought items for reliability and adjustability

# Front Axle

Intro/Update

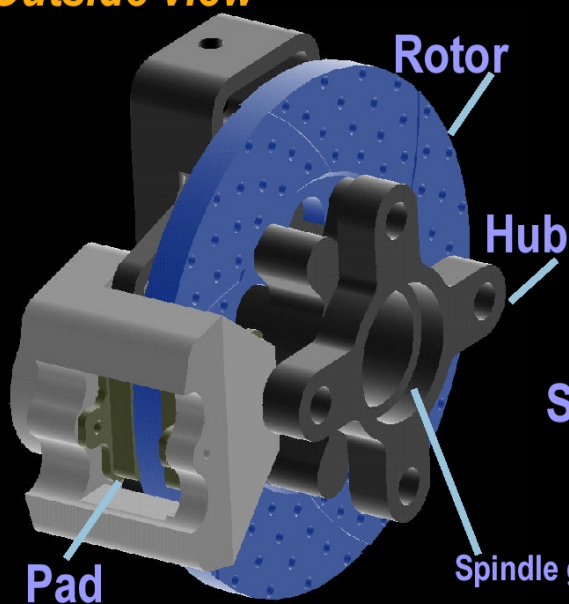
Front axle

Rear axle

Specifications

The Future

**Outside view**



Upright

**Inside view**

Steering arm attachment

Caliper

# Hub

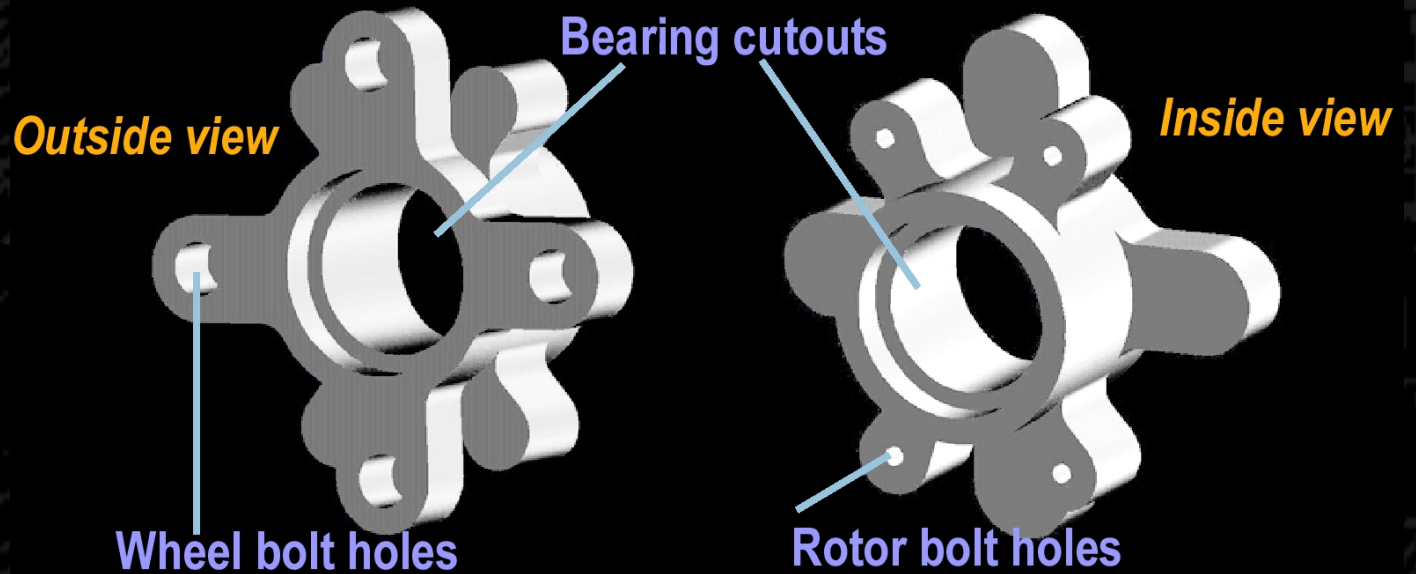
Intro/Update

Front axle

Rear axle

Specifications

The Future





# Front Brakes

Intro/Update

- Wilwood 1.75" single piston floating calipers

Front axle

- 7.5" diameter vented, cross-drilled, slotted, cast-iron rotors

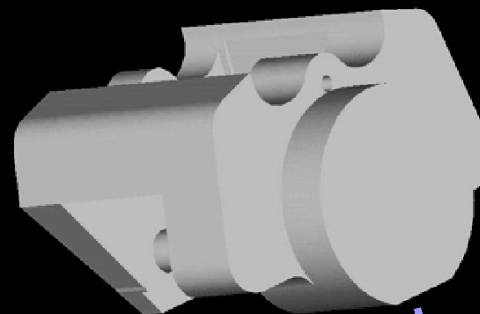
Rear axle

Specifications

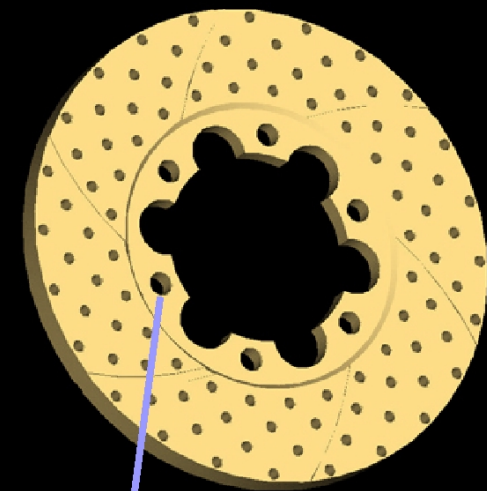
The Future



Brake pad



Caliper piston



Rotor mounting holes

# Brake Considerations

Intro/Update

- **Deceleration (1.2G design)**
  - dependent on fluid pressure, relative piston sizes, tire traction...

Front axle

- **Brake bias (60/40 design)**

Rear axle

- balance brake torque between front and rear tires

Specifications

- adjustable balance bar

The Future

- **Cooling**
  - 45 kJ of energy from 50 mph to 10 mph
  - about 20°C rise in rotor temperature per stop



# Steering System

Intro/Update

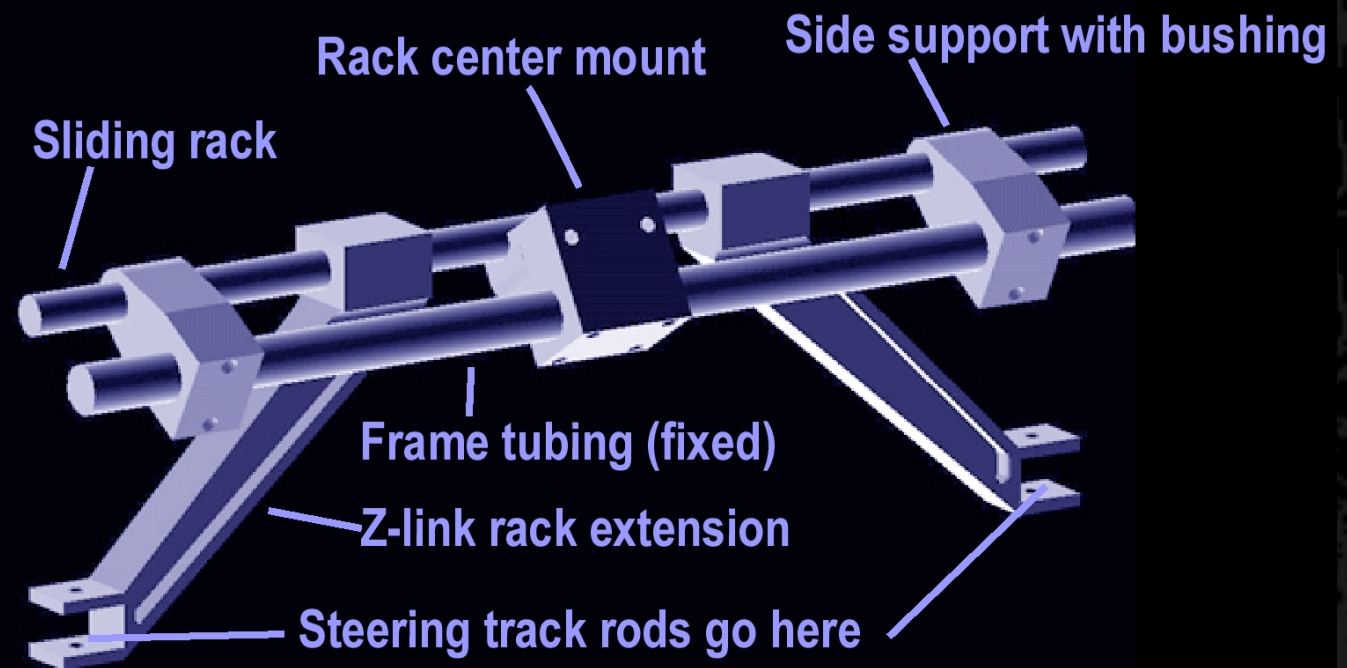
Front axle

Rear axle

Specifications

The Future

- Stiletto steering rack
- Alpha steering wheel (quick release)
- Various mounting components



# Steering Considerations

Intro/Update

- **Ratio**

- 3.6:1 to 3.3:1, less than 1 turn lock to lock

Front axle

- **Ackermann geometry**

- difference in steering angle between inside and outside tires

Rear axle

- inside tire turns more (smaller radius)

Specifications

- **Bump and compliance steer**

- wheels don't change direction over bumps or under load

The Future

- determined by relative locations of suspension and steering points

# Steering Outer Track Rod Attachment

Intro/Update

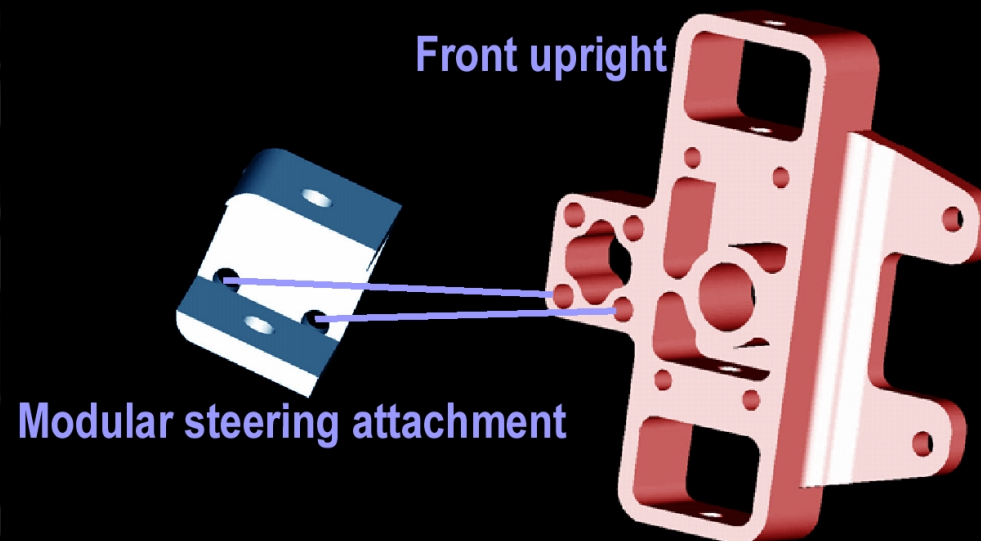
- **Modular attachment**
  - allows changes in steering geometry (Ackermann, bump steer, ratio) without refabricating the entire upright
  - reduces material usage

Front axle

Rear axle

Specifications

The Future





# Reynard Kinematics

Intro/Update

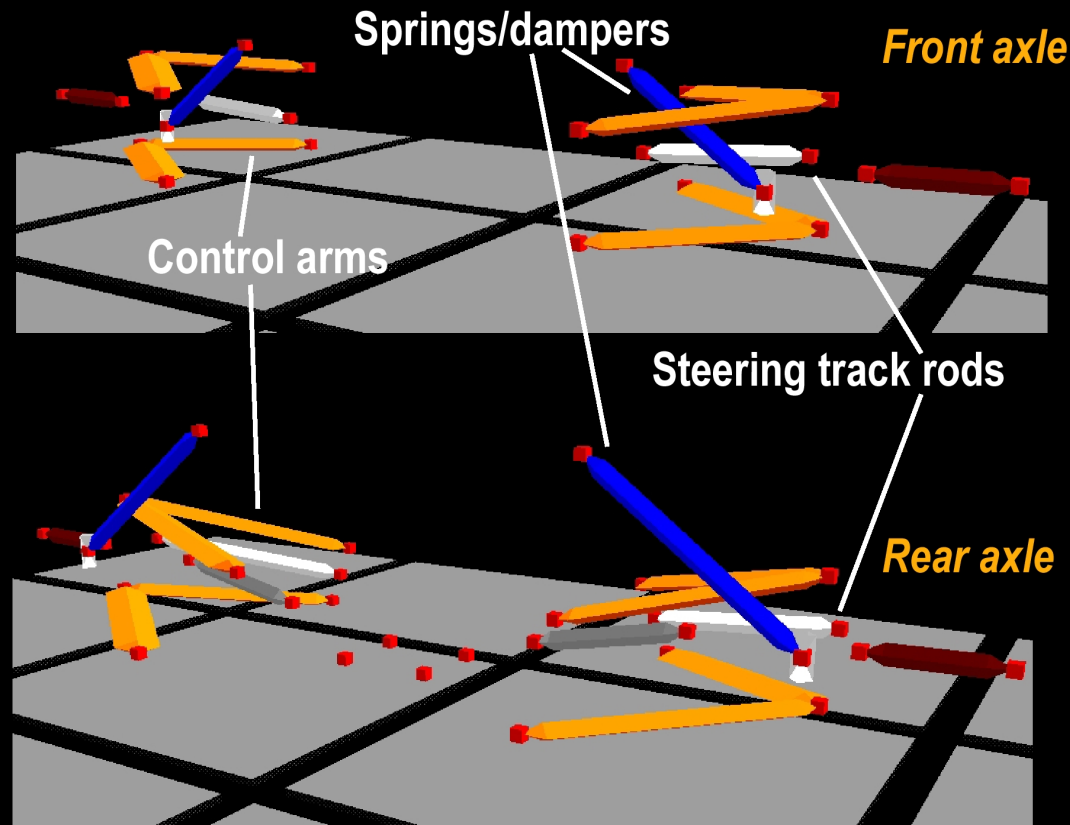
- Used to determine suspension and steering locations in pitch and roll

Front axle

Rear axle

Specifications

The Future



# Rear Axle

Intro/Update

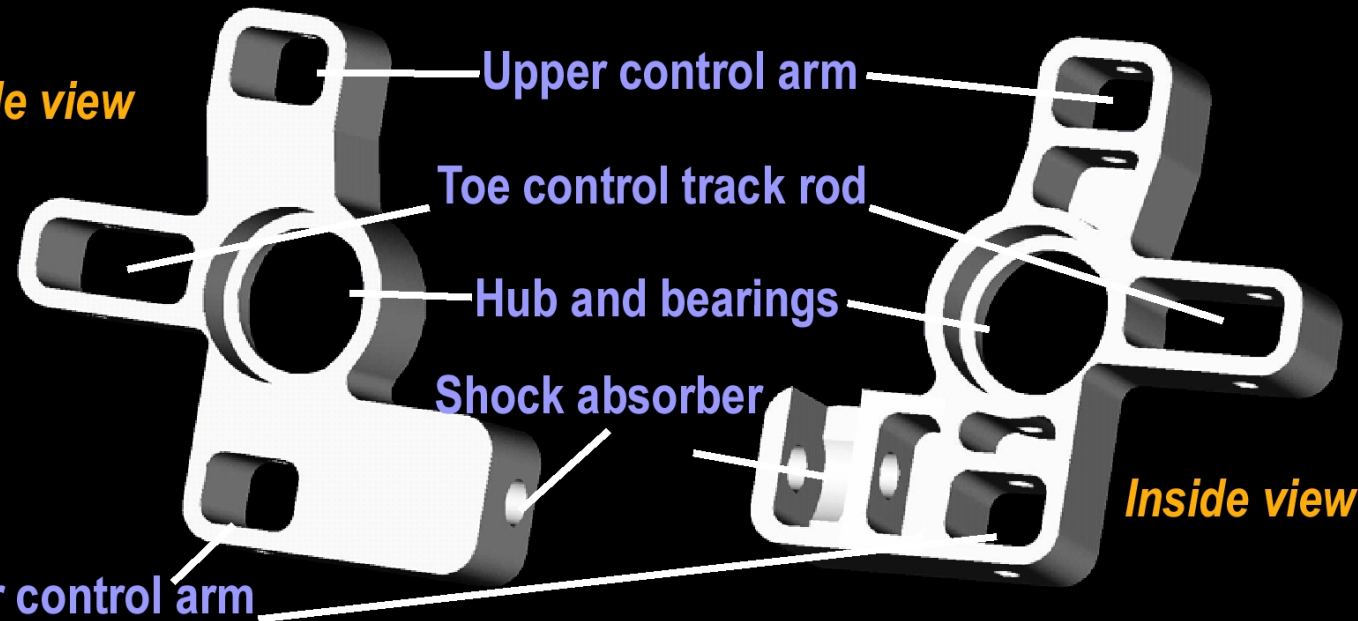
Front axle

Rear axle

Specifications

The Future

*Outside view*



*Inside view*

# Rear Shock Extension

Intro/Update

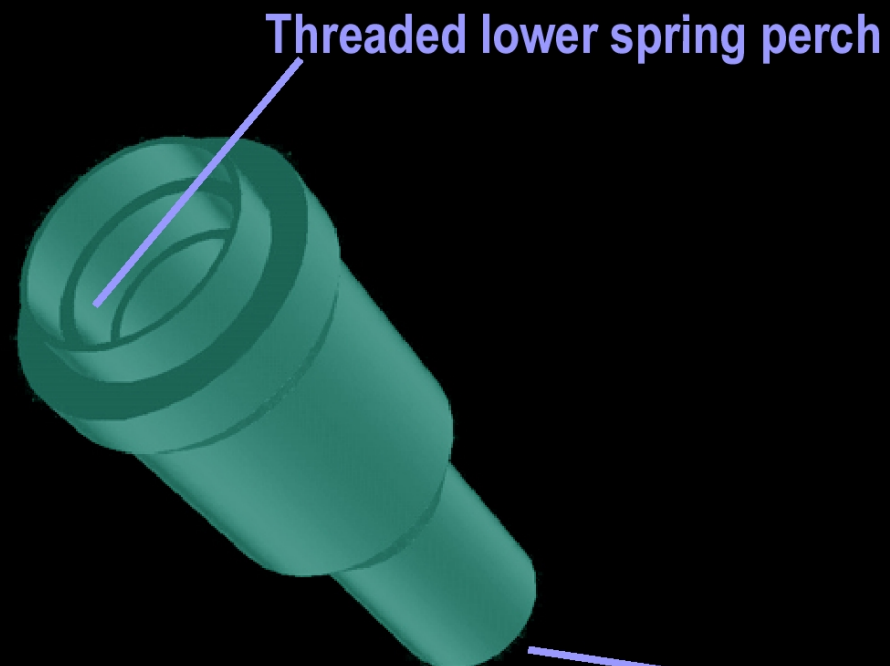
Front axle

Rear axle

Specifications

The Future

- Replaces lower spring perch and spherical bearing to gain adjustable length and flexibility



Threaded lower end for length adjustment to female rod end



# Rear Shock Mounting Points

Intro/Update

- Adjustable mounting points to balance car through corners

Front axle

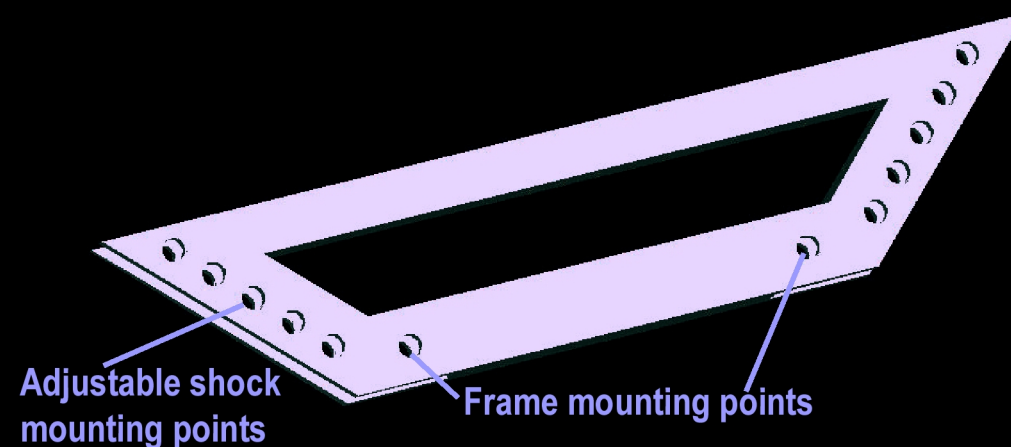
- Rear ride rate: 45 lb/in to 115 lb/in

Rear axle

- Use of locked spool axle requires different characteristics

Specifications

The Future



# Rear Axle Mount

Intro/Update

Front axle

Rear axle

Specifications

The Future

- Single inboard brake system
- Adjacent to drive chain and sprocket
- Adjustable position for chain tensioning



Rear axle plate for axle bearings and caliper

Hub for rear rotor



# Suspension Specifications

Intro/Update

Front axle

Rear axle

Specifications

The Future

- Track: 1200mm / 1130mm
- Tire size: 18x7.5x10
- Camber:  $-1^\circ$  /  $-1.5^\circ$
- Caster:  $8.1^\circ$
- Scrub radius: 51.5 mm
- Motion ratios: 1.75 / adjustable
- Roll gradient:  $1.6^\circ$  per G nominal
- Ride frequencies: 2.2 Hz / 2.8 Hz nominal
- Anti-dive/squat: 12%

	1	2	3	4	5	6	7	8	9	10	11	12	13	14
<b>Basic Vehicle Geometry and CG (Relative Location)</b>														
CG height	mm	12.4	12.5	12.4	12.5	12.4	12.5	12.4	12.5	12.4	12.5	12.4	12.5	12.4
Wheelbase	mm	1750	1750	1750	1750	1750	1750	1750	1750	1750	1750	1750	1750	1750
Track	mm	1130	1130	1130	1130	1130	1130	1130	1130	1130	1130	1130	1130	1130
<b>Vehicle Weight and Inertia</b>														
Weight	kg	1250	1250	1250	1250	1250	1250	1250	1250	1250	1250	1250	1250	1250
Wheel load	kg	312.5	312.5	312.5	312.5	312.5	312.5	312.5	312.5	312.5	312.5	312.5	312.5	312.5
<b>Vehicle Dynamic Characteristics</b>														
<b>Roll Frequency and Inertia Distribution</b>														
Roll frequency	Hz	2.2	2.2	2.2	2.2	2.2	2.2	2.2	2.2	2.2	2.2	2.2	2.2	2.2
Roll inertia	kg m <sup>2</sup>	3000	3000	3000	3000	3000	3000	3000	3000	3000	3000	3000	3000	3000
<b>Steering and Suspension</b>														
Steering ratio		1.5	1.5	1.5	1.5	1.5	1.5	1.5	1.5	1.5	1.5	1.5	1.5	1.5
Steering lock	deg	150	150	150	150	150	150	150	150	150	150	150	150	150
<b>Other Parameters</b>														
CG offset	mm	24	24	24	24	24	24	24	24	24	24	24	24	24
Roll resistance	kg m <sup>2</sup>	100	100	100	100	100	100	100	100	100	100	100	100	100
Roll damping	kg m <sup>2</sup> /s	100	100	100	100	100	100	100	100	100	100	100	100	100
<b>Anti-Dive and Squat</b>														
Anti-dive		0	0	0	0	0	0	0	0	0	0	0	0	0
Squat		0	0	0	0	0	0	0	0	0	0	0	0	0



# Steering Specifications

Intro/Update

- **Steering System**

Front axle

- **Ratio: 3.6:1 to 3.3:1**

- **Caster: 8.1°**

Rear axle

- **Scrub radius: 51.5 mm**

- **Steering wheel diameter: 250 mm**

Specifications

- **Perfect Ackermann until 26° of inside wheel steering**

The Future

# Brake Specifications

Intro/Update

Front axle

Rear axle

Specifications

The Future

- Design deceleration: 1.2G
- Design pedal force: 120 lb.
- Swept area: 350 sq. in. / ton
- Rotor diameter: 7.5 in. / 8.0 in.
- Hydraulic advantage: 11:1 / 8:1
- Mechanical advantage: 5.1:1
- Fluid line pressure: 750 psi / 500 psi
- Brake bias: 40 / 60 nominal

Design parameter	Value	Temperature (in. C)	19°
Design deceleration	1.2 G	Front line pressure	740 psi
Design pedal force	120 lb.	Rear line pressure	470 psi
Front rotor diameter	7.5 in.	Actual braking effort	59.9 lbf
Front rotor mass	4.2 lb.	Required balance of design	42.1 lb.
Front pad height	1.5 in.	Max braking torque - Front	42.1 lb-ft
Rear rotor diameter	8 in.	Max braking torque - Rear	239 lb-ft
Rear rotor mass	4.2 lb.	Max braking @ available at pedal force	1,000 lb-ft
Rear pad height	1.7 in.	Pedal travel for 600 lb pedal force	2.78 in.
Number of rear rotors	1		
Front caliper - number of pistons	1		
Front caliper diameter	1.78 in.		
Rear caliper - number of pistons	2	One side area of solid front rotor	44.2 sq. in.
Rear caliper diameter	1.78 in.	One side swept area of front rotor	28.2 sq. in.
Front master cylinder diameter	0.790 in.	Front rotor 1 side swept area	25.9 sq. in.
Rear master cylinder diameter	0.875 in.	Front rotor total swept area	43.6 sq. in.
Master cylinder travel under full brake application	0.050 in.	One side area of solid rear rotor	50.3 sq. in.
Front master cylinder to balance bar center	1.15 in.	Rear rotor 1 side swept area	32.2 sq. in.
Rear master cylinder to balance bar center	1 in.	Rear rotor total swept area	48.0 sq. in.
Wheelbase	66.9 in.	Total front piston area	430 sq. in.
Vehicle weight	400 lb.	Front master cylinder area	6.04 sq. in.
Front axle static load	225 lb.	Rear master cylinder area	6.50 sq. in.
Front tire diameter	18 in.	Fluid leverage ratio	5.10
Rear axle static load	275 lb.	Balance bar proportion P	0.47
Rear tire diameter	20 in.	Balance bar proportion R	0.53
CG to ground	20 in.	Force on balance bar	610 lb.
Coefficient of friction of tires	1.5	Front master cylinder force	327.3 lb.
Coefficient of friction of brakes	0.40	Rear master cylinder force	289.7 lb.
		Front brake fluid line pressure	740 psi
		Rear brake fluid line pressure	470 psi
		Front rotor clamping force	354 lb.
		Rear rotor clamping force	277 lb.
		Kinetic energy to absorb/dissipate	3493 lb-ft
		Kinetic energy to absorb/dissipate	4739 J
		Total rotor weight	13 lb.
		Temperature rise	35 °F
		Max force at front tire contact patches	469 lb.
		Max force at rear tire contact patches	34 lb.
		Max force at all contact patches	783 lb.
		Deceleration	1.20 G
		Front hydraulic advantage	11
		Rear hydraulic advantage	8
		Front rod displacement	0.5644 in.
		Pedal movement	2.777 in.
		Front axle load at design deceleration	179.6 lb.
		Rear axle load at design deceleration	273.4 lb.

# Future Work

Intro/Update

- **Successfully implemented suspension, steering, brake systems**

Front axle

- **Short term work:**

Rear axle

- **brake hydraulics**
- **rear axle items**

Specifications

- **Long term work:**

The Future

- **testing**
- **reliability vs. weight assessment**
- **re-evaluate many technical details to optimize the car**



# Recommendations

Intro/Update

- Full car model to resolve clearance details

Front axle

- Larger wheel diameter

Rear axle

Specifications

The Future

# Acknowledgments

Intro/Update

- The entire MAE department
  - too many people to list

Front axle

- Other Formula SAE teams

Rear axle

Specifications

The Future

# Questions

Intro/Update

Front axle

Rear axle

Specifications

The Future

